



# **Flex 8EX-Tandem Radio Control Equipment Instruction Manual**



**MAGNETEK**  
MATERIAL HANDLING  
**ENRANGE**

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# Service Information

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## PRODUCT MANUAL SAFETY INFORMATION

Magnetek, Inc. (Magnetek) offers a broad range of radio remote control products, control products and adjustable frequency drives, and industrial braking systems for material handling applications. This manual has been prepared by Magnetek to provide information and recommendations for the installation, use, operation and service of Magnetek's material handling products and systems (Magnetek Products). Anyone who uses, operates, maintains, services, installs or owns Magnetek Products should know, understand and follow the instructions and safety recommendations in this manual for Magnetek Products.

The recommendations in this manual do not take precedence over any of the following requirements relating to cranes, hoists lifting devices or other material handling equipment which use or include Magnetek Products:

- Instructions, manuals, and safety warnings of the manufacturers of the equipment where the radio system is used,
- Plant safety rules and procedures of the employers and the owners of facilities where the Magnetek Products are being used,
- Regulations issued by the Occupational Health and Safety Administration (OSHA),
- Applicable local, state or federal codes, ordinances, standards and requirements, or
- Safety standards and practices for the industries in which Magnetek Products are used.

This manual does not include or address the specific instructions and safety warnings of these manufacturers or any of the other requirements listed above. It is the responsibility of the owners, users and operators of the Magnetek Products to know, understand and follow all of these requirements. It is the responsibility of the employer to make its employees aware of all of the above listed requirements and to make certain that all operators are properly trained. **No one should use Magnetek Products prior to becoming familiar with and being trained in these requirements and the instructions and safety recommendations in this manual.**

## WARRANTY INFORMATION

For information on Magnetek's product warranties by product type, please visit [www.magnetekmh.com](http://www.magnetekmh.com).

# 1. INTRODUCTION

The Flex radio remote control systems are designed for control of industrial equipment and machinery such as overhead traveling cranes, jib cranes, gantry cranes, tower cranes, electric hoists, winches, monorails, conveyor belts, mining equipment and other material handling equipment where wireless control is preferred.

Each Flex system consists of a transmitter handset and receiver unit. Other standard-equipped accessories include transmitter waist belt, spare transmitter power key, clear vinyl pouch, "AA" alkaline batteries, compass direction decal sheet and user's manual.

List of notable features include:

- \* **62 user-programmable channels** – Advanced synthesized RF controls with 62 built-in channels; there are no more fixed channels and fragile quartz crystals to break.
- \* **Automatic channel scanning receiver** – No more hassle of climbing up the crane to change receiver channels.
- \* **Over one million unique ID codes (20bit)** – Each and every Flex system has its own unique ID codes and serial number; never repeats.
- \* **Advanced controls** – The Flex system utilizes advanced microprocessor controls with 32bit CRC and Hamming Code, which provide ultra fast, safe, precise, and error-free encoding and decoding.
- \* **Unique I-CHIP design** – The I-CHIP functions in a way that is very similar to SIM cards used on mobile phones, with the ability to transfer system information and settings from one transmitter to another without the hassle of resetting the spares.
- \* **Reliable push buttons** – The in-house designed push buttons with gold-plated contacts are rated for more than one million press cycles.
- \* **Low power consumption** – Requires only two "AA" Alkaline batteries for more than 100 hours of operating time between replacements.
- \* **Ultra-durable nylon and fiberglass composite enclosures** – Highly resistant to breakage and deformation even in the most abusive environments.
- \* **Full compliance** – All systems are fully compliant with the FCC Part-15 Rules, European Directives (Safety, EMC, R&TTE, Machinery), and Industry Canada Specifications (IC).

## 2. RADIO CONTROLLED SAFETY

### WARNINGS and CAUTIONS

Throughout this document WARNING and CAUTION statements have been deliberately placed to highlight items critical to the protection of personnel and equipment.

**WARNING** – A warning highlights an essential operating or maintenance procedure, practice, etc. which if not strictly observed, could result in injury or death of personnel, or long term physical hazards. Warnings are highlighted as shown below:



**CAUTION** – A caution highlights an essential operating or maintenance procedure, practice, etc. which if not strictly observed, could result in damage to, or destruction of equipment, or loss of functional effectiveness. Cautions are highlighted as shown below:



WARNINGS and CAUTIONS SHOULD NEVER BE DISREGARDED.

The safety rules in this section are not intended to replace any rules or regulations of any applicable local, state, or federal governing organizations. Always follow your local lockout and tagout procedure when maintaining any radio equipment. The following information is intended to be used in conjunction with other rules or regulations already in existence. It is important to read all of the safety information contained in this section before installing or operating the Radio Control System.

## 2.1. CRITICAL INSTALLATION CONSIDERATIONS



### WARNING

PRIOR TO INSTALLATION AND OPERATION OF THIS EQUIPMENT, READ AND DEVELOP AN UNDERSTANDING OF THE CONTENTS OF THIS MANUAL AND THE OPERATION MANUAL OF THE EQUIPMENT OR DEVICE TO WHICH THIS EQUIPMENT WILL BE INTERFACED. FAILURE TO FOLLOW THIS WARNING COULD RESULT IN SERIOUS INJURY OR DEATH AND DAMAGE TO EQUIPMENT.

ALL EQUIPMENT MUST HAVE A MAINLINE CONTACTOR INSTALLED AND ALL TRACKED CRANES, HOISTS, LIFTING DEVICES AND SIMILAR EQUIPMENT MUST HAVE A BRAKE INSTALLED. FAILURE TO FOLLOW THIS WARNING COULD RESULT IN SERIOUS INJURY OR DEATH AND DAMAGE TO EQUIPMENT.

AN AUDIBLE AND/OR VISUAL WARNING MEANS MUST BE PROVIDED ON ALL REMOTE CONTROLLED EQUIPMENT AS REQUIRED BY CODE, REGULATION, OR INDUSTRY STANDARD. THESE AUDIBLE AND/OR VISUAL WARNING DEVICES MUST MEET ALL GOVERNMENTAL REQUIREMENTS. FAILURE TO FOLLOW THIS WARNING COULD RESULT IN SERIOUS INJURY OR DEATH AND DAMAGE TO EQUIPMENT.

FOLLOW YOUR LOCAL LOCKOUT TAGOUT PROCEDURE BEFORE MAINTAINING ANY REMOTE CONTROLLED EQUIPMENT. ALWAYS REMOVE ALL ELECTRICAL POWER FROM THE CRANE, HOIST, LIFTING DEVICE OR SIMILAR EQUIPMENT BEFORE ATTEMPTING ANY INSTALLATION PROCEDURES. DE-ENERGIZE AND TAGOUT ALL SOURCES OF ELECTRICAL POWER BEFORE TOUCH-TESTING ANY EQUIPMENT. FAILURE TO FOLLOW THIS WARNING COULD RESULT IN SERIOUS INJURY OR DEATH AND DAMAGE TO EQUIPMENT.

THE DIRECT OUTPUTS OF THIS PRODUCT ARE NOT DESIGNED TO INTERFACE DIRECTLY TO TWO STATE SAFETY CRITICAL MAINTAINED FUNCTIONS, I.E., MAGNETS, VACUUM LIFTS, PUMPS, EMERGENCY EQUIPMENT, ETC. A MECHANICALLY LOCKING INTERMEDIATE RELAY SYSTEM WITH SEPARATE POWER CONSIDERATIONS MUST BE PROVIDED. FAILURE TO FOLLOW THIS WARNING COULD RESULT IN SERIOUS INJURY OR DEATH OR DAMAGE TO EQUIPMENT.

## 2.2. GENERAL

Radio controlled material handling equipment operates in several directions. Cranes, hoists, lifting devices and other material handling equipment can be large, and operate at high speeds. Quite frequently, the equipment is operated in areas where people are working in close proximity to the material handling equipment. **The operator must exercise extreme caution at all times.** Workers must constantly be alert to avoid accidents. The following recommendations have been included to indicate how careful and thoughtful actions may prevent injuries, damage to equipment, or even save a life.

## 2.3. PERSONS AUTHORIZED TO OPERATE RADIO CONTROLLED CRANES

Only properly trained persons designated by management should be permitted to operate radio controlled equipment.

Radio controlled cranes, hoists, lifting devices and other material handling equipment should not be operated by any person who cannot read or understand signs, notices and operating instructions that pertain to the equipment.

Radio controlled equipment should not be operated by any person with insufficient eyesight or hearing or by any person who may be suffering from a disorder or illness, is taking any medication that may cause loss of equipment control, or is under the influence of alcohol or drugs.

## **2.4. SAFETY INFORMATION AND RECOMMENDED TRAINING FOR RADIO CONTROLLED EQUIPMENT OPERATORS**

Anyone being trained to operate radio controlled equipment should possess as a minimum the following knowledge and skills before using the radio controlled equipment.

### The operator should:

- have knowledge of hazards pertaining to equipment operation
- have knowledge of safety rules for radio controlled equipment
- have the ability to judge distance of moving objects
- know how to properly test prior to operation
- be trained in the safe operation of the radio transmitter as it pertains to the crane, hoist, lifting device or other material handling equipment being operated
- have knowledge of the use of equipment warning lights and alarms
- have knowledge of the proper storage space for a radio control transmitter when not in use
- be trained in transferring a radio control transmitter to another person
- be trained how and when to report unsafe or unusual operating conditions
- test the transmitter emergency stop and all warning devices prior to operation; testing should be done on each shift, without a load
- be thoroughly trained and knowledgeable in proper and safe operation of the crane, hoist, lifting device, or other material handling equipment that utilizes the radio control
- know how to keep the operator and other people clear of lifted loads and to avoid “pinch” points
- continuously watch and monitor status of lifted loads
- know and follow cable and hook inspection procedures
- know and follow the local lockout and tagout procedures when servicing radio controlled equipment
- know and follow all applicable operating and maintenance manuals, safety procedures, regulatory requirements, and industry standards and codes

### The operator shall not:

- lift or move more than the rated load
- operate the material handling equipment if the direction of travel or function engaged does not agree with what is indicated on the controller
- use the crane, hoist or lifting device to lift, support or transport people
- lift or carry any loads over people
- operate the crane, hoist or lifting device unless all persons, including the operator, are and remain clear of the supported load and any potential pinch points
- operate a crane, hoist or lifting device when the device is not centered over the load
- operate a crane, hoist or lifting device if the chain or wire rope is not seated properly in the sprockets, drum or sheave

- operate any damaged or malfunctioning crane, hoist, lifting device or other material handling equipment
- change any settings or controls without authorization and proper training
- remove or obscure any warning or safety labels or tags
- leave any load unattended while lifted
- leave power on the radio controlled equipment when the equipment is not in operation
- operate any material handling equipment using a damaged controller because the unit may be unsafe
- operate manual motions with other than manual power
- operate radio controlled equipment when low battery indicator is on



## **WARNING**

THE OPERATOR SHOULD NOT ATTEMPT TO REPAIR ANY RADIO CONTROLLER. IF ANY PRODUCT PERFORMANCE OR SAFETY CONCERNS ARE OBSERVED, THE EQUIPMENT SHOULD IMMEDIATELY BE TAKEN OUT OF SERVICE AND BE REPORTED TO THE SUPERVISOR. DAMAGED AND INOPERABLE RADIO CONTROLLER EQUIPMENT SHOULD BE RETURNED TO MAGNETEK FOR EVALUATION AND REPAIR. FAILURE TO FOLLOW THIS WARNING COULD RESULT IN SERIOUS INJURY OR DEATH AND DAMAGE TO EQUIPMENT.

## **2.5. TRANSMITTER UNIT**

Transmitter switches should never be mechanically blocked ON or OFF. When not in use, the operator should turn the transmitter OFF. A secure storage space should be provided for the transmitter unit, and the transmitter unit should always be placed there when not in use. This precaution will help prevent unauthorized people from operating the material handling equipment.

Spare transmitters should be stored in a secure storage space and only removed from the storage space after the current transmitter in use has been turned OFF, taken out of the service area and secured.

## **2.6. PRE-OPERATION TEST**

**At the start of each work shift, or when a new operator takes control of the crane, operators should do, as a minimum, the following steps before making lifts with any crane or hoist:**

Test all warning devices.

**Test all direction and speed controls.**

Test the transmitter emergency stop.

## **2.7. BATTERIES**



### **WARNING**

KNOW AND FOLLOW PROPER BATTERY HANDLING, CHARGING AND DISPOSAL PROCEDURES. IMPROPER BATTERY PROCEDURES CAN CAUSE BATTERIES TO EXPLODE OR DO OTHER SERIOUS DAMAGE. FAILURE TO FOLLOW THIS WARNING COULD RESULT IN SERIOUS INJURY OR DEATH AND DAMAGE TO EQUIPMENT.

## **2.8. BATTERY HANDLING**

Use only batteries approved by Magnetek for the specific product.

Do not dispose of a battery pack in fire; it may explode.

Do not attempt to open the battery pack.

Do not short circuit the battery.

For intrinsically safe environments only use specified Magnetek intrinsically safe batteries.

Keep the battery pack environment cool during charging operation and storage (i.e., not in direct sunlight or close to a heating source).

## **2.9. BATTERY CHARGING**

For those transmitters equipped with battery chargers, please familiarize all users with the instructions of the charger before attempting to use.

Do not attempt to charge non-rechargeable battery packs.

Avoid charging partially discharged rechargeable batteries to help prolong battery cycle life.

Avoid charging the battery pack for more than 24 hours at a time.

Do not charge batteries in a hazardous environment.

Do not short the charger.

Do not attempt to charge a damaged battery.

Use only Magnetek approved chargers for the appropriate battery pack.

Do not attempt to use a battery that is leaking, swollen or corroded.

Charger units are not intended for outdoor use. Use only indoors.

## **2.10. BATTERY DISPOSAL**

Before disposing of batteries consult local and governmental regulatory requirements for proper disposal procedure.

## **2.11. SPECIFIC SYSTEM WARNINGS**

Below are some specific operating safety tips that should be strictly followed when operating a Flex 8EX-T System:

1. Check the Status LED on the transmitter for any signs of low battery power (refer to page 41).
2. Check the Status LED on the transmitter for any signs of irregularities (refer to page 41).
3. Make sure the system is not set to the same channel as any other Flex systems in use within a distance of 300 meters (900 feet).
4. Never operate a crane or equipment with two transmitter handsets at the same time.

# 3. GENERAL SYSTEM INFORMATION

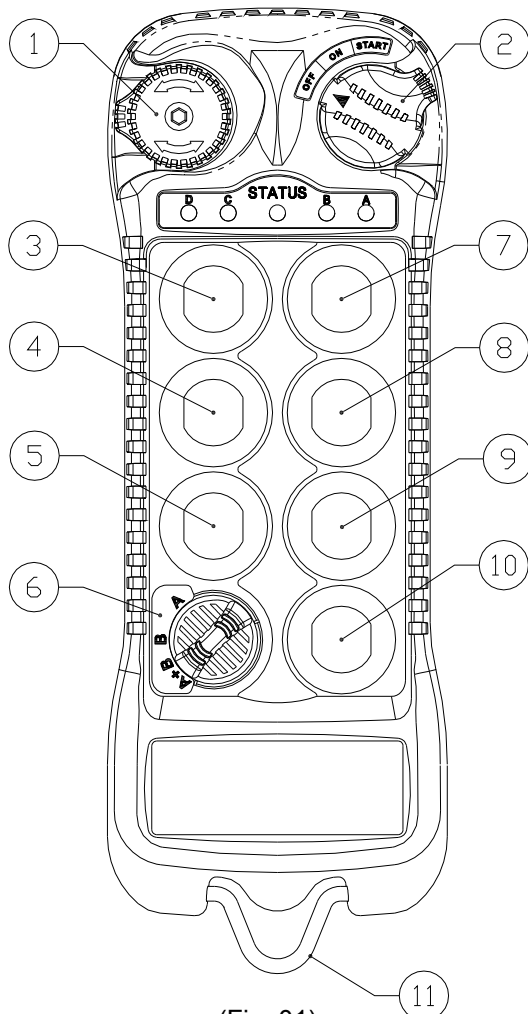
## 3.1. SYSTEM SETUP

The Flex 8EX-T system consists of two Flex 8EX-T transmitters with a rotary switch at the lower left position, two Flex 8EX-T transmitters with a plug in the lower left position, and two RXC-05 receiver units. In order to properly set up the Flex 8EX-T system, the following settings must be completed:

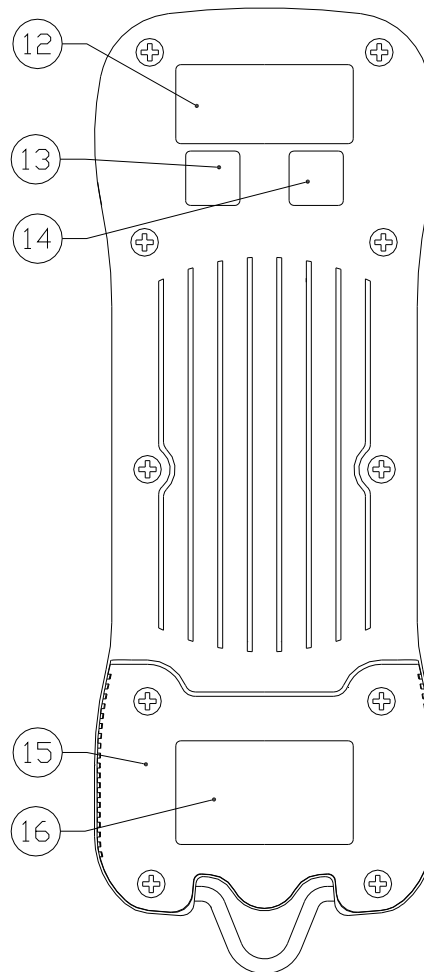
- 1.) Set Transmitter A and both Receiver A and B to the same channel.
- 2.) Set both receivers to 3-Channel scanning mode.
- 3.) Set Transmitter B two channels higher than Transmitter A.
- 4.) Set Tandem Transmitters to one channel higher than Transmitter A.
- 5.) Set Transmitter A to type 01, Transmitter B to type 02 and Tandem Transmitters to type 01.
- 6.) Set Receiver A to type 01 and Receiver B to type 02.

## 3.2. TRANSMITTER HANDSET

### 3.2.1. External Illustration (Standard Push Button Configuration)



(Fig. 01)

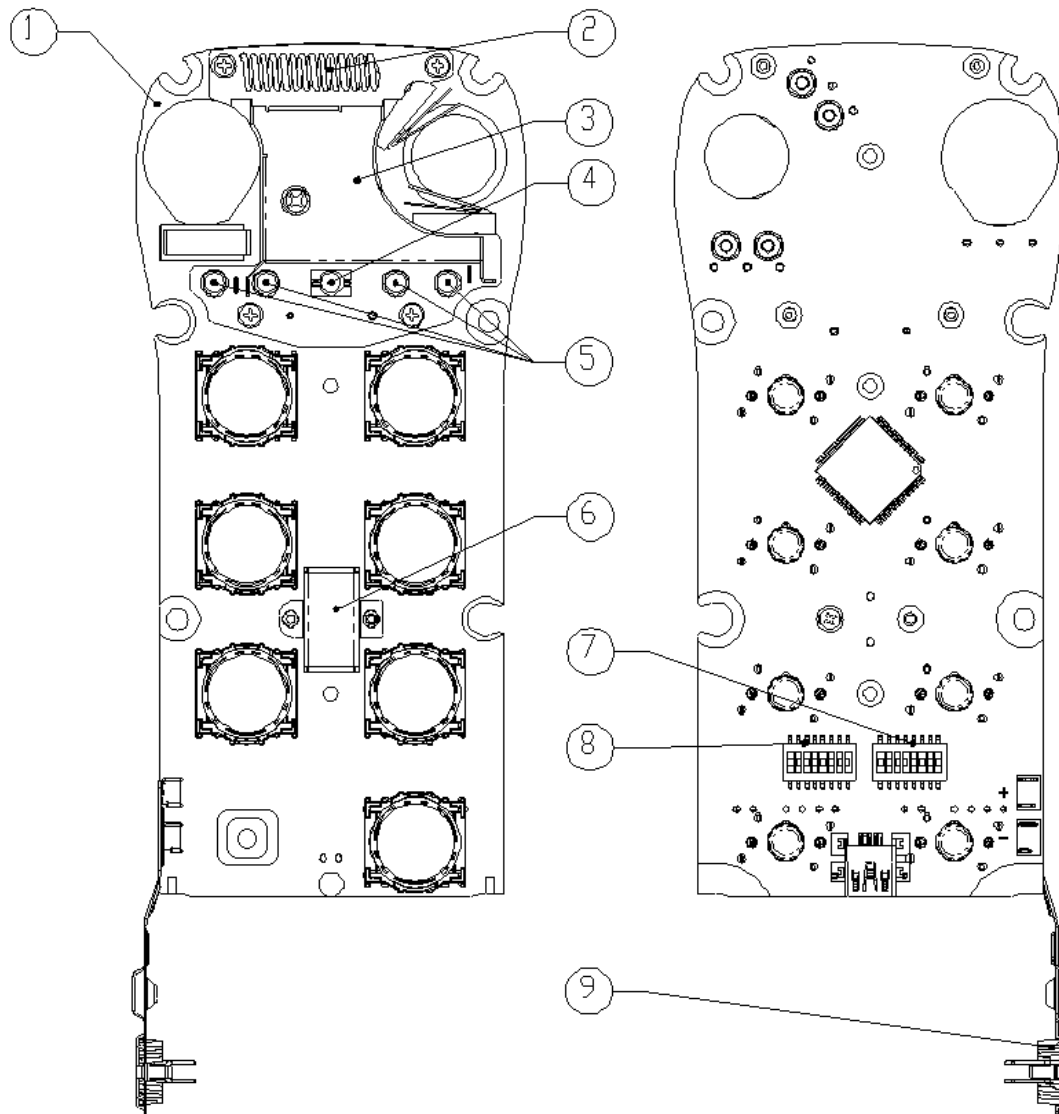


(Fig. 02)

- |    |                                 |     |                    |
|----|---------------------------------|-----|--------------------|
| 1. | Emergency Stop Button           | 9.  | Push Button #5     |
| 2. | Removable Power Key Switch      | 10. | Push Button #7     |
| 3. | Push Button #2                  | 11. | Strap Ring         |
| 4. | Push Button #4                  | 12. | System Information |
| 5. | Push Button #6                  | 13. | System Channel     |
| 6. | Select A, B, A+B Rotary Switch* | 14. | Crane Number       |
| 7. | Push Button #1                  | 15. | Battery Cover      |
| 8. | Push Button #3                  | 16. | FCC Information    |

\* Dedicated Transmitter does not have the Rotary Switch

### 3.2.2. Internal Illustration



(Fig. 03)

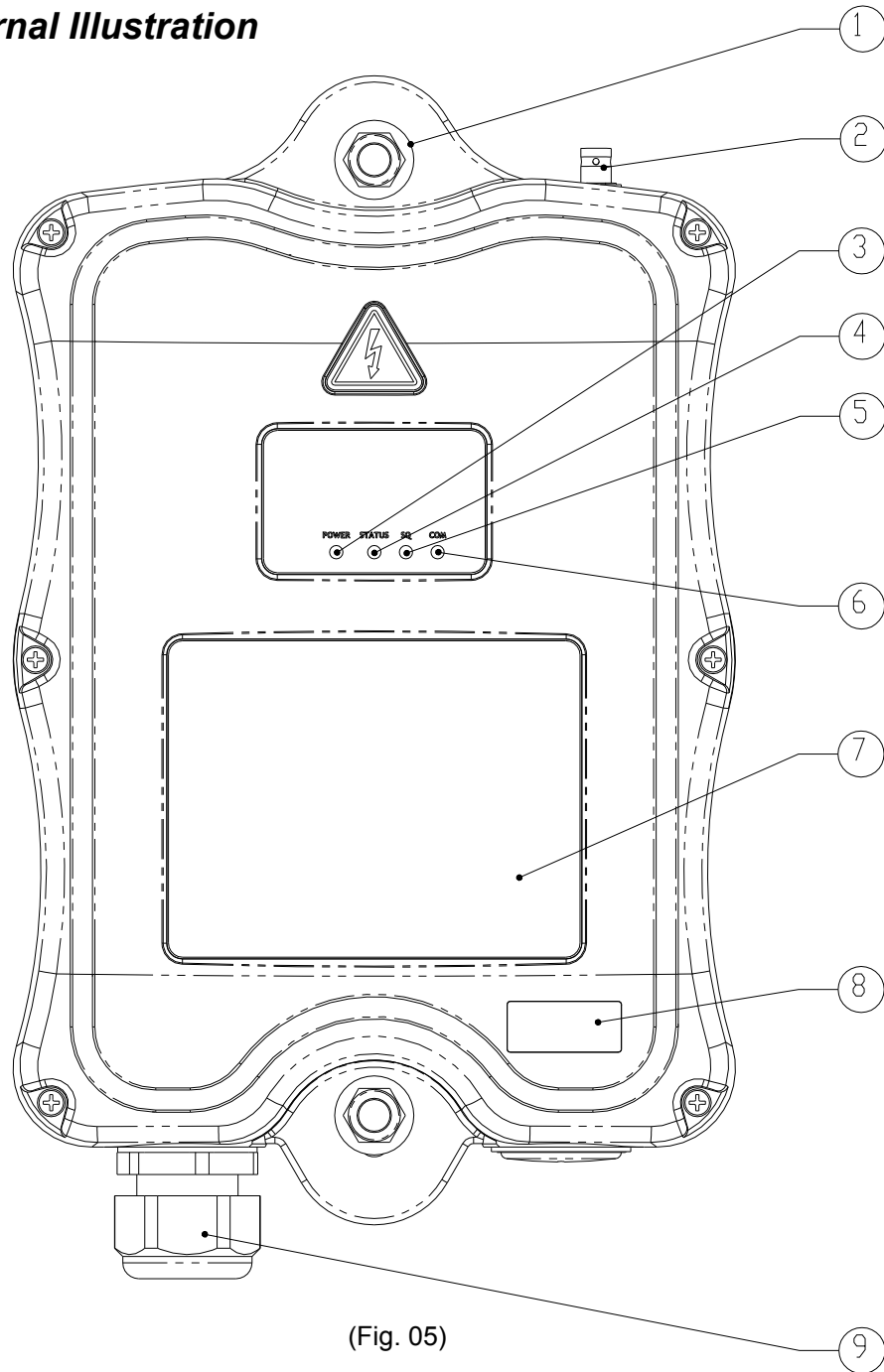
- 1. Encoder Board
- 2. Aerial Antenna
- 3. Transmitting Module
- 4. Status LED Display
- 5. Function LED Displays

(Fig. 04)

- 6. I-CHIP
- 7. Function Dip-Switch
- 8. Channel Dip-Switch
- 9. Battery Contact Mechanism

### 3.3. RECEIVER UNIT

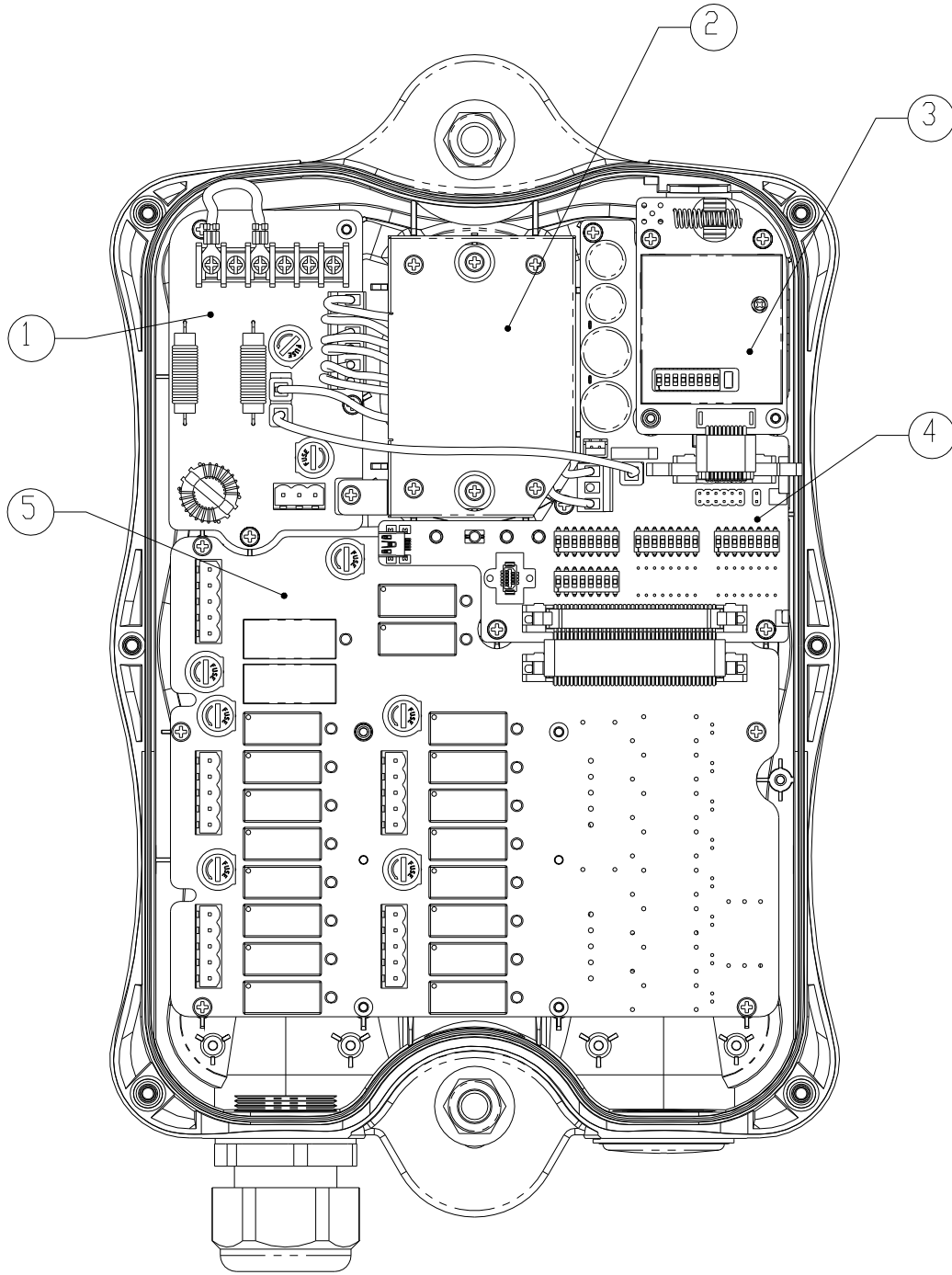
#### 3.3.1. External Illustration



(Fig. 05)

- |    |                       |    |                        |
|----|-----------------------|----|------------------------|
| 1. | Shock Mount           | 6. | COM LED Display        |
| 2. | External Antenna Jack | 7. | Output Contact Diagram |
| 3. | Power LED Display     | 8. | System Information     |
| 4. | Status LED Display    | 9. | Cord Grip              |
| 5. | SQ LED Display        |    |                        |

### 3.3.2. Internal Illustration



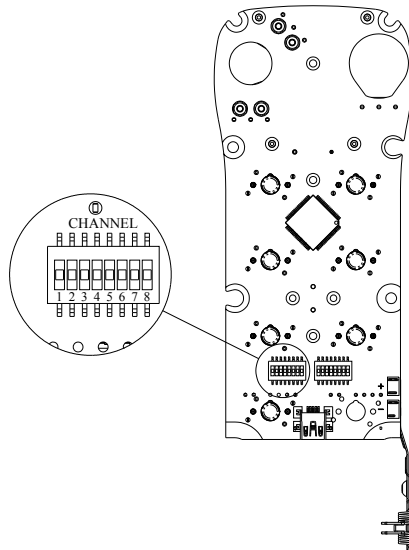
(Fig. 06)

- |    |                   |    |                    |
|----|-------------------|----|--------------------|
| 1. | AC Line Filter    | 4. | Decoder Module     |
| 2. | Power Transformer | 5. | Output Relay Board |
| 3. | Receiving Module  |    |                    |

# 4. FUNCTION SETTINGS

## 4.1. TRANSMITTER HANDSET

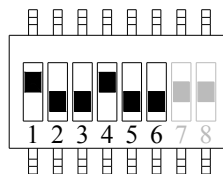
### 4.1.1. System Channel Settings



(Fig. 07)

Set the transmitter channel by adjusting the channel dip-switch located on the backside of the transmitter encoder board (refer to Fig. 07 above). Only the first six (6) positions are used for channel programming (refer to Fig. 08 below). The system channels table located on page 32 illustrates which dip-switch setting corresponds to which channel. Once the transmitter channel is altered, make sure to change the receiver channel as well. The channel on both the transmitter and receiver must be identical in order for the system to work. To change the receiver channel please refer to page 23.

**Example:**



Top slot → "1"

Bottom slot → "0"

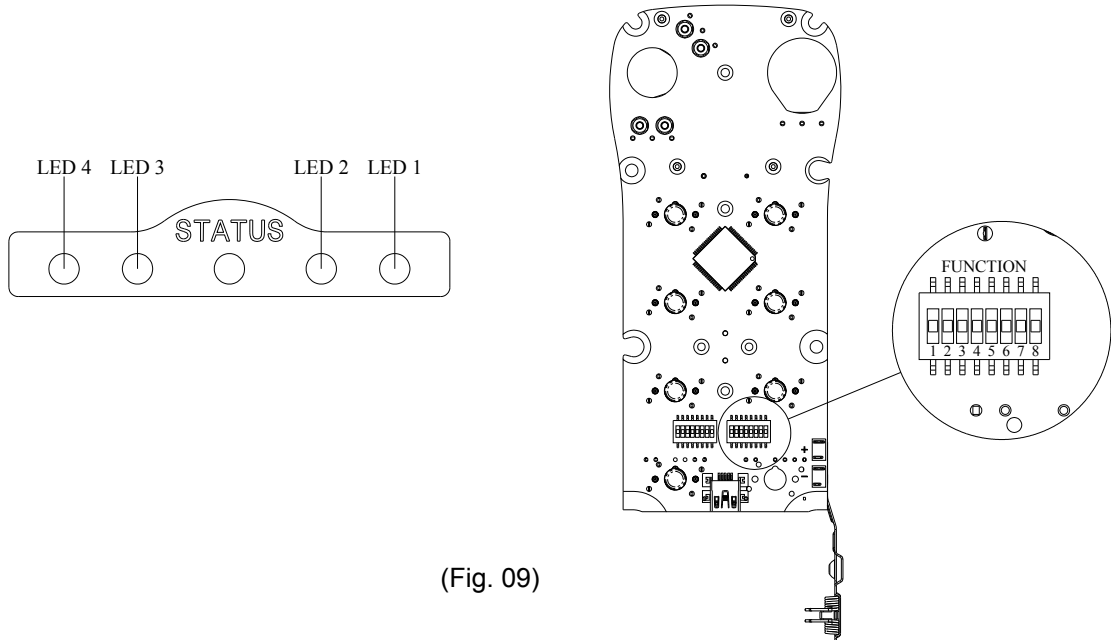
(Fig. 08)

The above dip-switch setting "1 0 0 1 0 0" corresponds to "channel 36" in the system channels table on page 32.

## 4.1.2. Push Button Functions with LED Displays

### 4.1.2.1. Standard Push Button Configuration (Transmitter Toggle)

Set the transmitter toggle (latching output relay) function by adjusting the 8-position function dip-switch located on the backside of the transmitter encoder board (refer to Fig. 09 below). The LED 1 through LED 4 shown inside the shaded box (see below) illustrates which LED on the transmitter will light up when the designated push button (PB5 - PB7) is pressed.



(Fig. 09)

	DIP	PB5	PB6	PB7
<b>1</b>	00000000	Normal	Normal	Normal
<b>2</b>	00000101	Normal	Normal	Normal
<b>3</b>	00000110	Normal	Normal	LED 3
<b>4</b>	00000111	Normal	LED 2	LED 3
<b>5</b>	00001000	LED 1	LED 2	LED 3

\* PB5...PB7 → Push button number

\* Normal → Normal momentary contact

\* LED 1...LED 4 → Transmitter toggled with designated LED Display

### 4.1.2.2. Standard Push Button Configuration (A/B Selector)

There are four (4) different types of A/B selector sequences available on the Flex system. Choose the one that is most suitable for your application.

Type-A selector sequence : A+B → A → B → A+B ...  
 Type-B selector sequence : Off → A → B → Off → A → B ...  
 Type-C selector sequence : A → B → A+B → A → B → A+B ...  
 Type-D selector sequence : Off → A → B → A+B → Off → A → B → A+B ...

	DIP	PB5	PB6	PB7
<b>6</b>	00101111	Normal	Normal	A/1&2
<b>7</b>	00110000	Normal	Normal	B/1&2
<b>8</b>	00110001	Normal	Normal	C/1&2
<b>9</b>	00110010	Normal	Normal	D/1&2
<b>10</b>	00110011	Normal	Normal	Normal
<b>11</b>	00110100	Normal	Normal	Normal
<b>12</b>	00110101	Normal	Normal	Normal
<b>13</b>	00110110	Normal	Normal	Normal
<b>14</b>	00110111	Normal	Normal	A/1&2
<b>15</b>	00111000	Normal	Normal	A/1&2
<b>16</b>	00111001	Normal	Normal	A/1&2
<b>17</b>	00111010	Normal	Normal	A/1&2
<b>18</b>	00111011	Normal	Normal	B/1&2
<b>19</b>	00111100	Normal	Normal	B/1&2
<b>20</b>	00111101	Normal	Normal	B/1&2
<b>21</b>	00111110	Normal	Normal	C/1&2
<b>22</b>	00111111	Normal	Normal	C/1&2
<b>23</b>	01000000	Normal	Normal	D/1&2

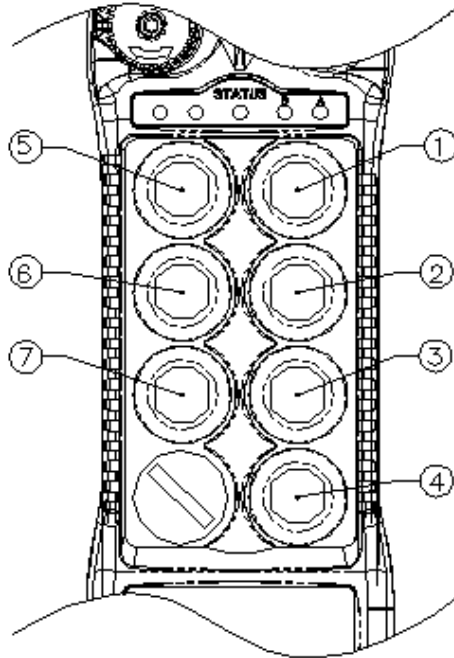
\* PB5...PB7 → Push button number

\* Normal → Normal momentary contact

\* A/1&2...D/3&4 → A/B Selector type with designated LED Display (LED 1&2 or LED 3&4)

### 4.1.2.3. Inline Push Button Configuration (Transmitter Toggle)

The push button arrangement for inline push button setup starts from top to bottom and then from the right column to the left column (refer to Fig. 10 below). To set the inline push button configuration, please refer to JP4 and JP5 jumpers setting on page 30. With inline push button configurations, PB1 & PB2 still corresponds to output relay K1~K4, PB3 & PB4 corresponds to relay K5~K8, etc.



(Fig. 10)

	DIP	PB5	PB6	PB7
<b>24</b>	00000000	Normal	Normal	Normal
<b>25</b>	00000101	Normal	Normal	Normal
<b>26</b>	00010100	Normal	Normal	LED 3
<b>27</b>	00010101	Normal	LED 2	LED 3
<b>28</b>	00010110	LED 1	LED 2	LED 3

\* PB5...PB7 → Push button number

\* Normal → Normal momentary contact

\* LED 1...LED 4 → Transmitter toggled with designated LED Display

#### 4.1.2.4. **Inline Push Button Configuration (A/B Selector)**

There are four (4) different types of A/B selector sequences available on the Flex system. Choose the one that is most suitable for your application.

Type-A selector sequence : A+B → A → B → A+B ...  
 Type-B selector sequence : Off → A → B → Off → A → B ...  
 Type-C selector sequence : A → B → A+B → A → B → A+B ...  
 Type-D selector sequence : Off → A → B → A+B → Off → A → B → A+B ...

	DIP	PB5	PB6	PB7
<b>29</b>	01110011	Normal	Normal	A/1&2
<b>30</b>	01110100	Normal	Normal	B/1&2
<b>31</b>	01110101	Normal	Normal	C/1&2
<b>32</b>	01110110	Normal	Normal	D/1&2
<b>33</b>	00110011	Normal	Normal	Normal
<b>34</b>	00110100	Normal	Normal	Normal
<b>35</b>	00110101	Normal	Normal	Normal
<b>36</b>	00110110	Normal	Normal	Normal
<b>37</b>	01110111	Normal	Normal	A/1&2
<b>38</b>	01111000	Normal	Normal	A/1&2
<b>39</b>	01111001	Normal	Normal	A/1&2
<b>40</b>	01111010	Normal	Normal	A/1&2
<b>41</b>	01111011	Normal	Normal	B/1&2
<b>42</b>	01111100	Normal	Normal	B/1&2
<b>43</b>	01111101	Normal	Normal	B/1&2
<b>44</b>	01111110	Normal	Normal	C/1&2
<b>45</b>	01111111	Normal	Normal	C/1&2
<b>46</b>	10000000	Normal	Normal	D/1&2

\* PB5...PB7 → Push button number

\* Normal → Normal momentary contact

\* A/1&2...D/3&4 → A/B Selector type with designated LED Display (LED 1&2 or LED 3&4)

### 4.1.3. Optional 4-Digit Security Code

The 4-digit Security Code is an optional feature that can be programmed into the transmitter to allow operation only to those who know the code. If this feature is desired, set up as follows: Prior to rotating the transmitter power key-switch to the START position to begin operation, you first enter a 4-digit security code in order to proceed further. When this 4-digit security code is entered correctly, a green light will appear on the Status LED. Please refer to the instructions below on how to program the 4-digit security code.

- a. Release the E-Stop, press and hold PB1, PB2, PB3 and PB4 (all at once), and then rotate the power key to START position.



- b. A constant orange light will appear on the Status LED telling you that you are in the security code programming mode.
- c. For newly purchased systems with the security code function deactivated (default setting), press PB1 four times (1111) to activate the security code function. At this time the Status LED on the transmitter will blink orange slowly telling you that the four digits entered is correct. Then select your own 4-digit security code by pressing PB1, PB2, PB3 or PB4 on the transmitter (four presses randomly). At this time, fast orange blinks are displayed on the Status LED telling you to reconfirm the 4-digit security code you have just entered. A green light will appear once you have re-entered the same 4-digit security code again (programming completed). If any mistake is made during this process, or if a red light is shown on the Status LED after you have re-entered the security code (incorrect input), or even if you believe you have entered the correct code but the transmitter fails to work properly, then you must reset the transmitter power (by power-cycling the transmitter\*) and then repeat steps a, b and c again.

*\*NOTE: To power-cycle the transmitter, you must first remove, then reinstall the batteries. Simply turning the power switch off, then on will NOT properly clear the memory. This process must be used for any errors regarding proper transmitter operation (not just for security code settings).*

*Steps: Press and hold PB1~PB4 and rotate power key to START position → constant orange → press PB1 four times (for new systems) or 4-digit security code → slow orange blinks → enter the new 4-digit security code → fast orange blinks → re-enter the same 4-digit security code again → green light.*

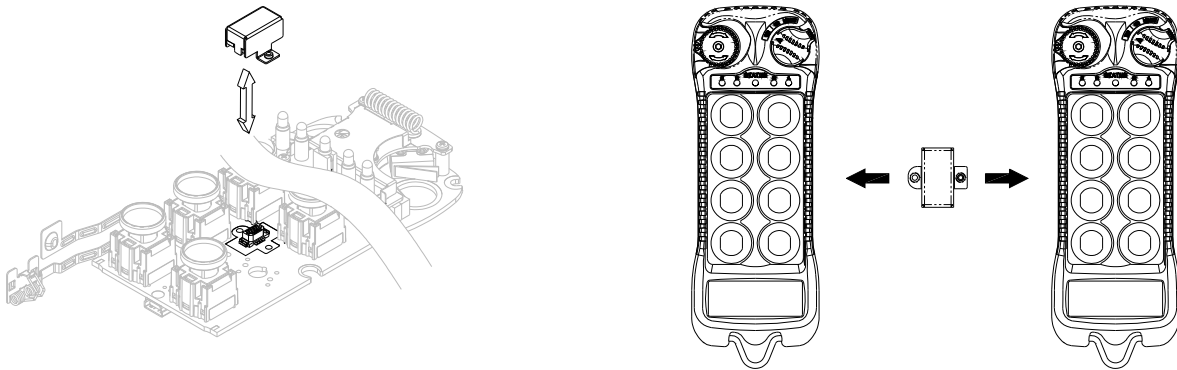
- d. If you wish to cancel the security code function, then repeat steps a, b, and c above and press PB1 four times as your new security code (security code function disabled).
- e. If you do not remember the 4-digit security code, then you must contact your dealer or distributor for further assistance.

#### 4.1.4. I-CHIP

The I-CHIP functions in a way that is very similar to a SIM card inside a mobile phone, which stores system information such as your telephone number, account number, phone book and other settings. The I-CHIP works exactly the same way, as it stores information such as system serial number/ID codes, channel configurations and push button configurations.

When replacing a transmitter handset, just take the I-CHIP out of the old transmitter and install it into the new one (refer to Fig. 11 below). For a complete information transfer, make sure both the Channel and Function dip-switches are set to all "1". If both dip-switches are set to all "1", then the transmitter will operate according to the push button configurations and channel stored inside the I-CHIP. If both the Channel and the Function dip-switches are set to values other than all "1", then the transmitter will operate according to the channel and push button configurations set on these two dip-switches, not the ones stored inside the I-CHIP. Every time the settings on these two dip-switches are changed, the new settings will be stored into the I-CHIP automatically. In this case the previous channel and push button configurations stored inside the I-CHIP will be erased and be replaced by the new settings.

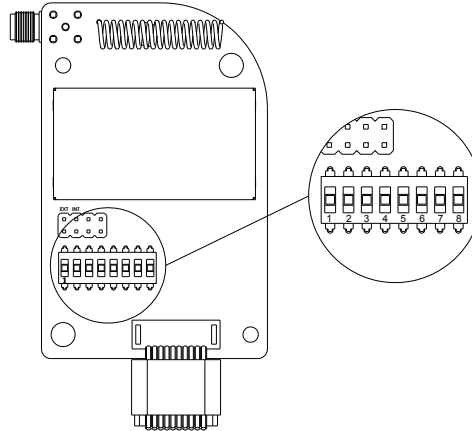
For safety purposes, the system serial number/ID code stored inside the I-CHIP cannot be changed directly on the transmitter encoder board. Only channels and push button configurations can be changed directly on the encoder board via Channel and Function dip-switches. There are only two ways that you can change transmitter serial number/ID codes: 1) via the I-CHIP programming port located on the decoder module inside the receiver unit (please refer to page 31 on how to program the I-CHIP [serial number/ID code] via receiver unit) or 2) via an external I-CHIP programmer or duplicator unit available from the factory. Please ask your local dealer for assistance if your system requires serial number/ID code adjustments.



(Fig. 11)

## 4.2. RECEIVER UNIT

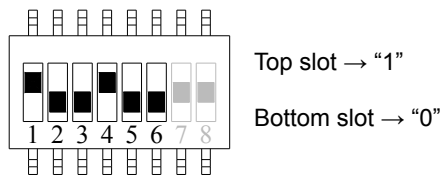
### 4.2.1. System Channel Settings



(Fig. 12)

Set the receiver channel by adjusting the channel dip-switch located on the receiver module (refer to Fig. 12 above); only the first six (6) positions are used for channel programming (refer to Fig. 13 below). The system channels table located on page 32 illustrates which dip-switch setting corresponds to which channel. Once the receiver channel is altered make sure to change the transmitter channel as well. The channel on both the transmitter and the receiver must be identical in order for system to work. To change the transmitter channel please refer to page 16.

**Example:**



(Fig. 13)

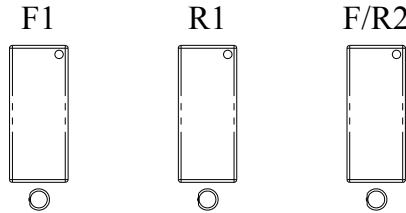
The above dip-switch setting “1 0 0 1 0 0” corresponds to “channel 36” in the system channels table on page 32.

## 4.2.2. Output Relay Configurations

### 4.2.2.1. Output Relay Types

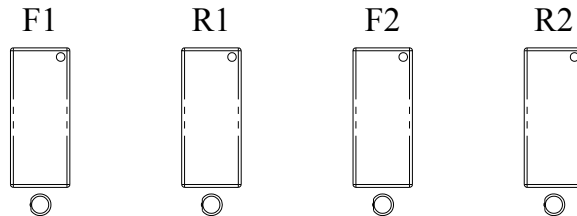
1. **Three (3) output relays per motion – shared 2<sup>nd</sup> speed output relay**

Output relays with Forward 1<sup>st</sup> speed (F1), Reverse 1<sup>st</sup> speed (R1) and Forward/Reverse 2<sup>nd</sup> speed (F/R2). Forward and Reverse 2<sup>nd</sup> speed (F/R2) share the same output relay.



2. **Four (4) output relays per motion – separate 1<sup>st</sup> and 2<sup>nd</sup> speed output relays**

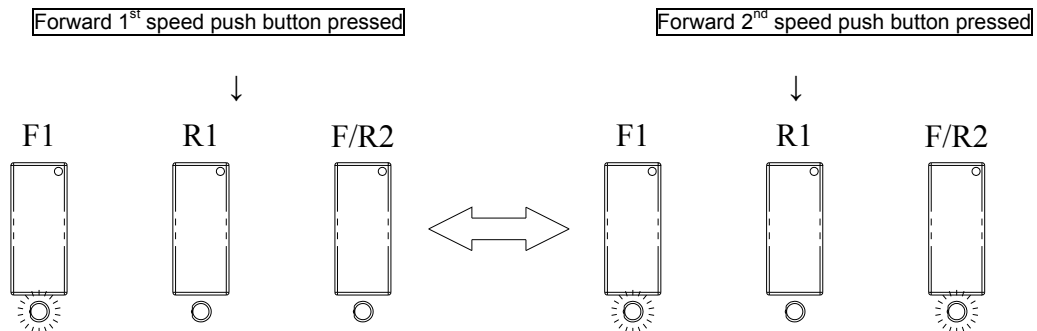
Output relays with Forward 1<sup>st</sup> speed (F1), Reverse 1<sup>st</sup> speed (R1), Forward 2<sup>nd</sup> speed (F2) and Reverse 2<sup>nd</sup> speed (R2). Forward and Reverse 2<sup>nd</sup> speed with separate output relays.



### 4.2.2.2. Output Relay Actions at 2<sup>nd</sup> Speed

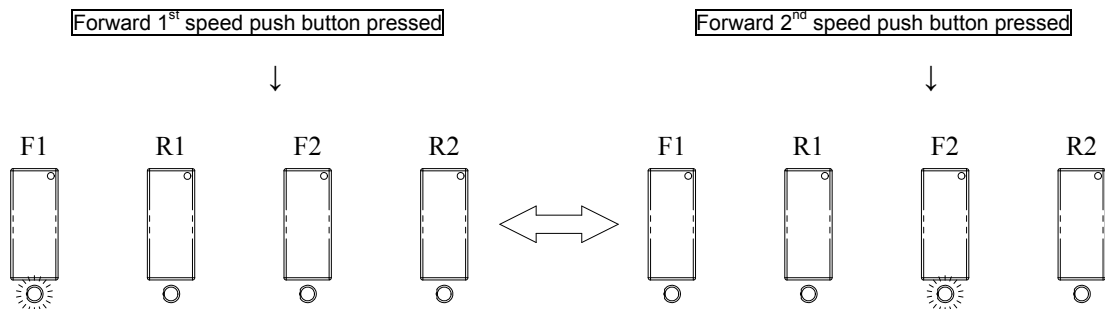
1. **3-output relays configuration with Closed/Closed contact at 2<sup>nd</sup> speed**

At 2<sup>nd</sup> speed, both 1<sup>st</sup> speed (F1 or R1) and 2<sup>nd</sup> speed (F/R2) output relays are closed (refer to page 27 on how to set to this function).



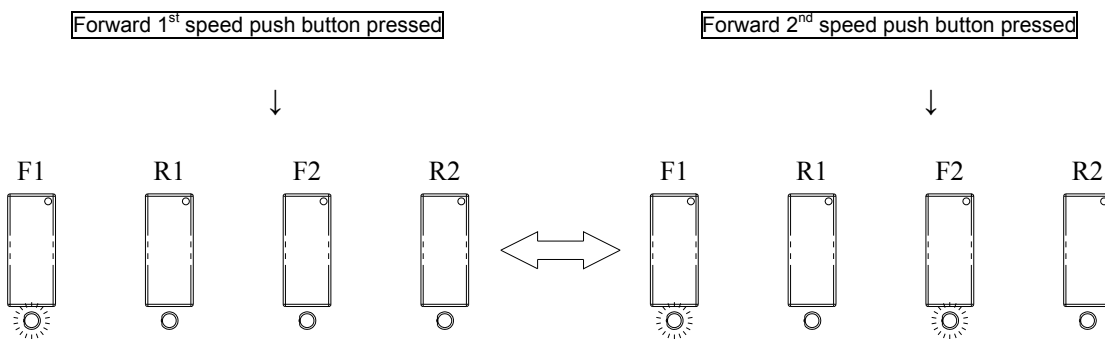
## 2. 4-output relays configuration with Opened/Closed contact at 2<sup>nd</sup> speed

At 2<sup>nd</sup> speed, only the 2<sup>nd</sup> speed (F2 or R2) output relay is closed (refer to page 28 on how to set to this function).



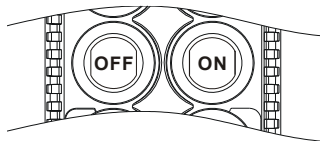
## 3. 4-output relays configuration with Closed/Closed contact at 2<sup>nd</sup> speed

At 2<sup>nd</sup> speed, both 1<sup>st</sup> speed (F1 or R1) and 2<sup>nd</sup> speed (F2 or R2) output relays are closed (refer to page 28 on how to set to this function).



### 4.2.2.3. ON/OFF Push Button Function

The user can set any of the two adjacent push buttons on the transmitter to behave like a mechanical ON & OFF rocker switch (refer to page 28 on how to set to this function). When "On" output relay is closed ("On" push button pressed), the "Off" output relay will open automatically, or vice versa.

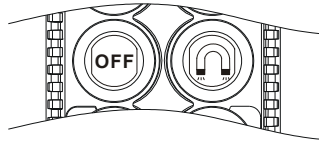


#### **4.2.2.4. START/AUX Function**

After initiating the START function the Start position will become an auxiliary function with momentary contact. For auxiliary applications such as horns or buzzers, please connect it to the FUNC output relay (wire #6) located inside the receiver unit.

#### **4.2.2.5. Magnet ON/OFF Push Button Function**

The user can set any of the two adjacent push buttons on the transmitter to control a magnet. To activate the magnet just press the push button with the Magnet symbol. To deactivate the magnet, for safety purpose, you must first press and hold the Magnet push button and then press the OFF push button. Pressing the OFF push button by itself cannot deactivate the magnet (refer to page 28 on how to set to this function).



#### **4.2.2.6. Brake Function**

When the transmitter push button is released from 2<sup>nd</sup> speed up to 1<sup>st</sup> speed, both 1<sup>st</sup> and 2<sup>nd</sup> speed output relays will open for up to 1.0 second and then with 1<sup>st</sup> speed output relay closed thereafter (refer to page 28 on how to set to this function).

#### **4.2.2.7. Momentary Contact**

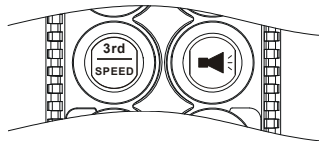
When the push button is released the output relay that corresponds to that push button will open (refer to page 29 on how to set to this function). This type of contact is usually applied to external applications such as horns or buzzers.

#### **4.2.2.8. Toggled Contact**

When the push button is released the output relay that corresponds to that push button will remained closed (maintained contact) until next time the user presses the same push button again (refer to page 29 on how to set to this function). This type of contact is usually applied to external applications such as lights.

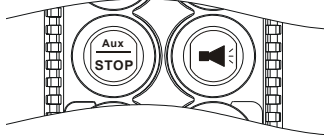
#### **4.2.2.9. 3<sup>rd</sup> Speed Push Button Function**

This function allows the crane to travel an additional step beyond 2<sup>nd</sup> speed. For example, if the operator is pressing the “UP” push button down to 2<sup>nd</sup> speed, pressing the 3<sup>rd</sup> speed push button (with “UP” push button still held at 2<sup>nd</sup> speed) will toggle between 2<sup>nd</sup> speed and 3<sup>rd</sup> speed (refer to page 29 on how to set to this function).



### 4.2.2.10. Auxiliary STOP Push Button Function

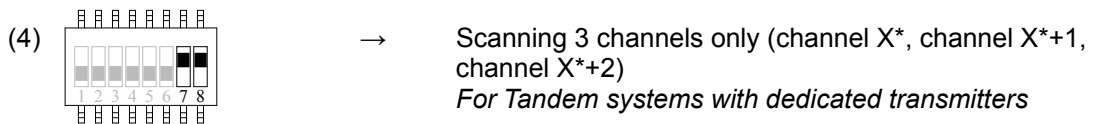
The auxiliary STOP function acts as a 2<sup>nd</sup> emergency stop button. Other than by emergency stop button and transmitter power key switch, the receiver MAIN is also deactivated when this auxiliary stop push button is pressed (refer to page 29 on how to set to this function).



### 4.2.3. Receiver Auto-Scanning Settings

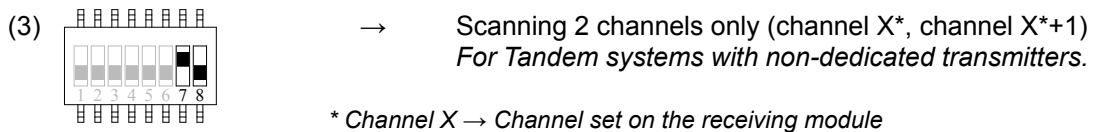
#### Receiver Channel Dip-switch

*NOTE: The tandem receiver is set to 3-channel scanning by default*



**Example:** If the first 6 dip-switch positions on the receiving module is set to Ch.01 (“000000” or “000001”), when set to 3-channel scanning (type-4 above), then the receiver will only scan Ch.01, Ch.02 and Ch. 03.

*NOTE: On tandem systems that do not have dedicated transmitters, the default channel scanning setting is 2-channel scanning (or type 3 below). This is not recommended to be set when using tandem systems with dedicated transmitters.*

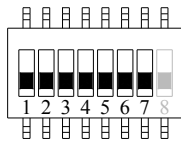


*NOTE: Tandem systems cannot utilize channel scanning type 1 and 2. Tandem systems must be set to either scanning type 4 or type 3 as shown above to function properly.*

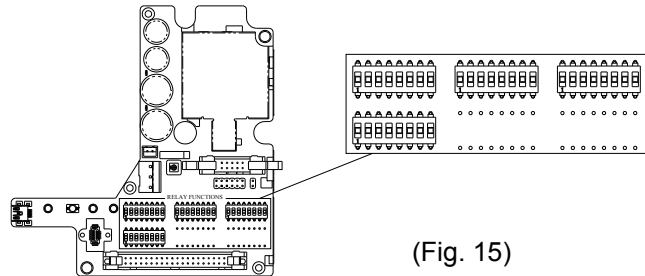
## 4.2.4. Dip-Switch Settings

### 4.2.4.1. Interlocked Functions

Interlocked means the two adjacent push buttons cannot be activated simultaneously as they will cancel each other out. Interlocked settings are usually applied to a crane's forward and reverse motions. Each dip-switch on the decoder module corresponds to one (1) motion or two (2) adjacent push buttons (refer to Fig. 14 & 15 below). Only the first seven (7) dip-switch positions are used (counting from left to right); the 8<sup>th</sup> dip-switch position (far right) is not used.



(Fig. 14)



(Fig. 15)

■ Manufacture preset

Dip Settings	Function Descriptions	# of Relays Used
0000000	Normal (single speed only, F2 & R2 relays not used).	2
0000001	Closed/Closed Relay Action at 2 <sup>nd</sup> Speed (separate 2 <sup>nd</sup> speed relay).	4
0000010	Closed/Closed Relay Action at 2 <sup>nd</sup> Speed (shared 2 <sup>nd</sup> speed relay).	3
0000011	Opened/Closed Relay Action at 2 <sup>nd</sup> Speed (separate 2 <sup>nd</sup> speed relay).	4
0000110	On (right button) & Off (left button).	2
0001000	On & Off affected by the E-stop command. When the E-stop command is initiated, the Off relay is activated.	2
0001001	On + Start / Off + Start -- Prior to pressing the button you must first rotate and hold the power key switch at START position to activate On or Off relays.	2
0001010	FWD/REV toggled (latched).	2
0001011	FWD/REV toggled (latched) and affected by the E-stop command.	2
0000111	Safety Magnet On & Off.	2
0100001	Closed/Closed + Brake.	4
0100010	Closed/Closed Relay Action + Brake.	3
0100011	Opened/Closed Relay Action + Brake.	4

### 4.2.4.2. Non-Interlocked Functions

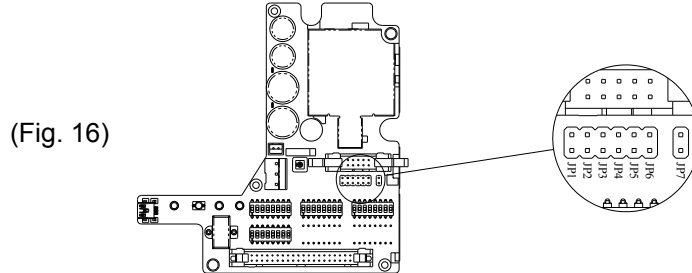
Contrary to interlocked settings, non-interlocked settings allow the two adjacent push buttons be used simultaneously. Non-interlocked settings are usually applied to a crane's auxiliary functions such as lights, horns, 3<sup>rd</sup> speed, auxiliary stops and Pitch & Catch. Each dip-switch on the decoder module corresponds to one (1) motion or two (2) adjacent push buttons (left & right push buttons).

Function Code	Dip Position Setting #1	Dip Position Setting #2 - #4 (left button) & #5 - #7 (right button)	Function Description
A	1	000	Normal (momentary) contact.
B	1	001	Toggled (latching) contact.
C	1	010	Acceleration (3 <sup>rd</sup> speed).
D	1	011	Toggled (latching) contact affected by the E-Stop command. When E-Stop command is initiated, all toggled (latching) relays are also deactivated.
E	1	101	Pitch & Catch Type-1. When Pitch (release) function is initiated, receiver MAIN will not be deactivated. <b>(Not available in tandem system)</b>
F	1	110	Pitch & Catch Type-2. When Pitch (release) function is initiated, receiver MAIN will be deactivated. <b>(Not available in tandem system)</b>
G	1	111	Auxiliary Stop.
H	1	100	Normal + Start function. For added safety, you must first rotate and hold the power key switch at "START" position and then press the intended push button at the same time to activate the output relay.

- Example #1: Left button (set to function code A) / right button (set to function code A) → **1 000 000**  
 Example #2: Left button (set to function code B) / right button (set to function code B) → **1 001 001**  
 Example #3: Left button (set to function code A) / right button (set to function code C) → **1 000 010**  
 Example #4: Left button (set to function code F) / right button (set to function code A) → **1 110 000**

## 4.2.5. Jumper Settings

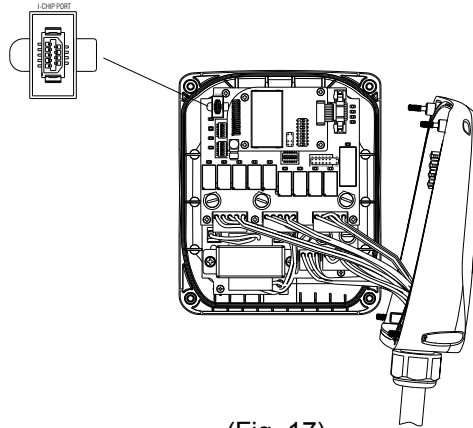
Jumper settings are applied to functions such as mainline-disconnect time, Start function, transmitter push button layout, system information (serial number/ID code) programming and system testing. The jumpers #1- #7 are located on the decoder module above the four (4) dip-switches (refer to Fig.16 below).



■ Manufacture preset

Jumper Settings		Function
JP1 (Blank)	JP2 (Blank)	Receiver MAIN remains closed until the transmitter power is turned off or emergency stop command is initiated.
JP1 (Inserted)	JP2 (Blank)	Receiver MAIN opens after 5 minutes of system inactivity.
JP1 (Blank)	JP2 (Inserted)	Receiver MAIN opens after 30 minutes of system inactivity.
JP1 (Inserted)	JP2 (Inserted)	Receiver MAIN opens after 60 minutes of system inactivity.
JP3 (Blank)		Press any push button on the transmitter to activate the receiver MAIN at system startup, after E-stop reset, and after system inactivity (refer to JP1 & JP2 settings above).
JP3 (Inserted)		Rotate the power key switch to "START" position to activate the receiver MAIN at system startup, after E-stop reset, and after system inactivity (refer to JP1 & JP2 settings above).
JP4 (Blank)	JP5 (Blank)	Standard right-to-left push button configuration for all models.
JP4 (Inserted)	JP5 (Blank)	In-line push button configuration (top to bottom) for Flex 8ES/EX.
JP4 (Blank)	JP5 (Inserted)	In-line push button configuration (top to bottom) for Flex 12ES/EX.
JP4 (Inserted)	JP5 (Inserted)	In-line push button configuration (top to bottom) for Flex 4ES/EX.
JP6 (Blank)		Program system serial number/ID code and channel from decoder module to I-CHIP.
JP6 (Inserted)		Program system serial number/ID code and channel from I-CHIP to decoder module.
JP7 (Inserted)		For system test only, receiver MAIN disabled.

## 4.2.6. I-CHIP Programming Port



(Fig. 17)

The I-CHIP programming port located on the decoder module (refer to Fig. 17 above) inside the receiver is designed for the purpose of transferring system serial number/ID codes either from the I-CHIP to the receiver or vice versa. If you wish to transfer system information from the receiver to the I-CHIP, just insert the I-CHIP onto the programming port (JP6 jumper not inserted), wait until the Status LED on the decoder module turns a constant green (within 2 seconds), and then take the I-CHIP out of the programming port (programming completed). At this time the I-CHIP should also possess the same serial number/ID code as the receiver. If the Status LED on the decoder module displays a constant red light after inserting the I-CHIP (programming failed), then you must reinsert the I-CHIP one more time. On the other hand, if you wish to transfer system information from the I-CHIP to the receiver, then you must first insert JP6 jumper prior to inserting the I-CHIP and wait for the green light to appear on the Status LED. At this time the receiver should also possess the same system information as the I-CHIP. Please note that the receiver unit must be powered in order to proceed with the programming.

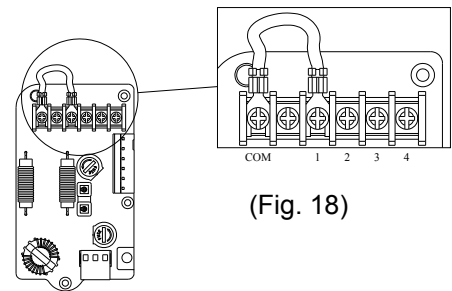
## 4.2.7. Voltage Settings

Always check the voltage setting is correct for your application prior to installation (refer to Fig. 18 below).

- Position 1 → 110-120 VAC
- Position 2 → 220-240 VAC or 24 VAC\*
- Position 3 → 380-400 VAC or 42 VAC\*
- Position 4 → 410-460 VAC or 48 VAC\* or 12-24 VDC\*\*

\* For system with 24/42/48 VAC power supply.

\*\* For system with 12 – 24 VDC power supply.



(Fig. 18)

## 4.2.8. Fuse Ratings

FUSE #	110 – 120 VAC	220 – 240 VAC	380 – 400 VAC	410 – 460 VAC	24 VAC	42 & 48 VAC	12 – 24 VDC
F9	1.0A (red)	1.0A (red)	1.0A (red)	0.5A (blue)	3.0A (yellow)	2.0A (purple)	2.0A (purple)
F10	1.0A (red)	1.0A (red)	1.0A (red)	0.5A (blue)	3.0A (yellow)	2.0A (purple)	2.0A (purple)

\* Output relay fuse → 5.0A (clear)

## 5. SYSTEM CHANNELS TABLE

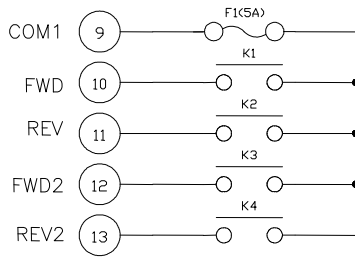
Channel	Frequency	Dip-switch Setting	Channel	Frequency	Dip-switch Setting
01	433.000MHZ	000000	32	433.775MHZ	100000
01	433.000MHZ	000001	33	433.800MHZ	100001
02	433.025MHZ	000010	34	433.825MHZ	100010
03	433.050MHZ	000011	35	433.850MHZ	100011
04	433.075MHZ	000100	36	433.875MHZ	100100
05	433.100MHZ	000101	37	433.900MHZ	100101
06	433.125MHZ	000110	38	433.925MHZ	100110
07	433.150MHZ	000111	39	433.950MHZ	100111
08	433.175MHZ	001000	40	433.975MHZ	101000
09	433.200MHZ	001001	41	434.000MHZ	101001
10	433.225MHZ	001010	42	434.025MHZ	101010
11	433.250MHZ	001011	43	434.050MHZ	101011
12	433.275MHZ	001100	44	434.075MHZ	101100
13	433.300MHZ	001101	45	434.100MHZ	101101
14	433.325MHZ	001110	46	434.125MHZ	101110
15	433.350MHZ	001111	47	434.150MHZ	101111
16	433.375MHZ	010000	48	434.175MHZ	110000
17	433.400MHZ	010001	49	434.200MHZ	110001
18	433.425MHZ	010010	50	434.225MHZ	110010
19	433.450MHZ	010011	51	434.250MHZ	110011
20	433.475MHZ	010100	52	434.275MHZ	110100
21	433.500MHZ	010101	53	434.300MHZ	110101
22	433.525MHZ	010110	54	434.325MHZ	110110
23	433.550MHZ	010111	55	434.350MHZ	110111
24	433.575MHZ	011000	56	434.375MHZ	111000
25	433.600MHZ	011001	57	434.400MHZ	111001
26	433.625MHZ	011010	58	434.425MHZ	111010
27	433.650MHZ	011011	59	434.450MHZ	111011
28	433.675MHZ	011100	60	434.475MHZ	111100
29	433.700MHZ	011101	61	434.500MHZ	111101
30	433.725MHZ	011110	62	434.525MHZ	111110
31	433.750MHZ	011111	<b>I-CHIP</b>		111111*

\* When set to all "1" the priority goes to the channel assigned inside the I-CHIP.

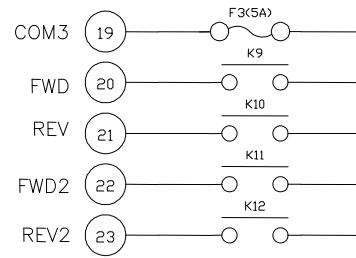
# 6. RECEIVER INSTALLATION

## 6.1 OUTPUT RELAY CONTACT DIAGRAM

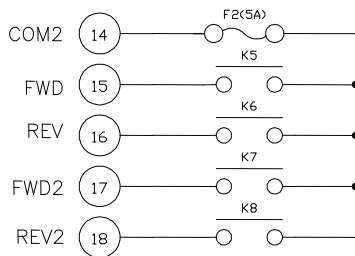
Push button 1~2



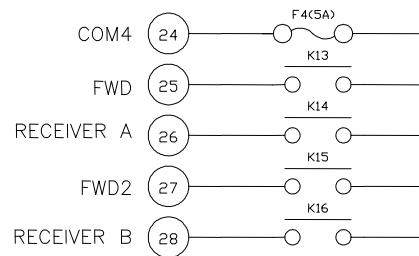
Push button 5~6



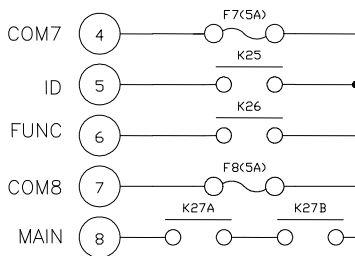
Push button 3~4



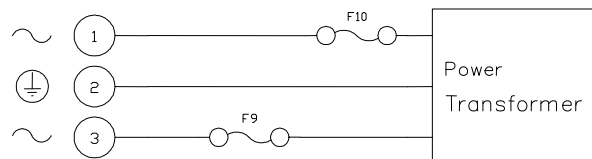
Push button 7~8



MAIN ID Function



Power

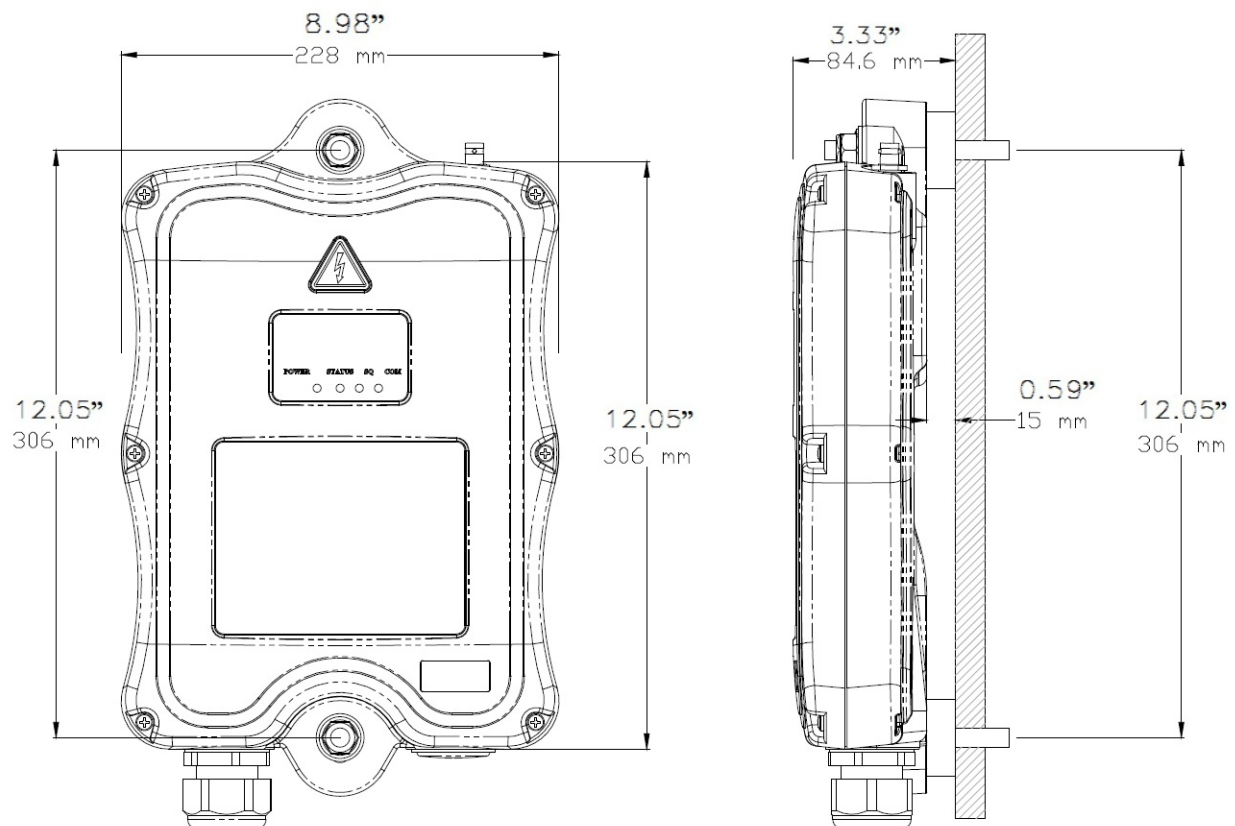


- \* For the 3-relay (shared 2<sup>nd</sup> speed) and 4-relay (separate 2<sup>nd</sup> speed) configuration please refer to pages 24-25.
- \* For the 4-relay closed/closed and 4-relay opened/closed relay configuration please refer to pages 24-25.
- \* For different voltage settings please refer to page 31.
- \* For F9 and F10 power fuse ratings please refer to page 31.
- \* For 12-24 VDC power supply, wire #1 corresponds to the negative charge (-) and wire #3 corresponds to the positive charge (+). Wire #2 is for GROUND.

## 6.2 PRE-INSTALLATION PRECAUTIONS

1. Make sure the transmitter and the receiver have identical serial number/ID codes and channels.
2. Make sure the receiver is not set to the same channel as any other systems in use in the surrounding area.
3. Make sure that the crane or equipment is working properly prior to installation.
4. Make sure the power source to the receiver is set correctly.
5. Switch off the main power source to the crane or equipment prior to installation.

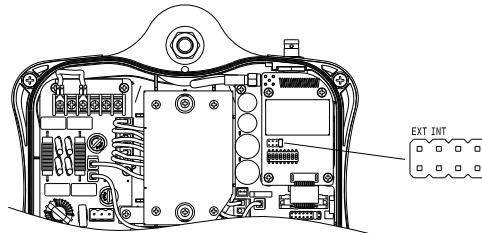
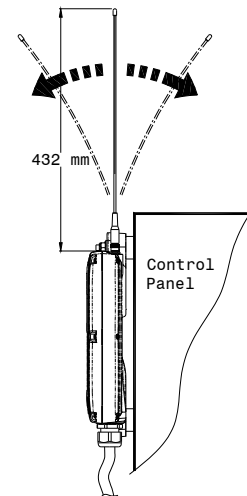
## 6.3 STEP-BY-STEP INSTALLATION



(Fig. 19)

1. For best reception the location of the receiver should be visible to the operator at all time.
2. The location selected should not be exposed to high levels of electric noise. Mounting the receiver next to an unshielded variable frequency drive may cause minor interference. Always locate the receiver as far away from variable frequency drives as possible.

3. Ensure the selected location has adequate space to accommodate the receiver (refer to Fig. 19 on page 34). If an external antenna is used, always locate the receiver where the antenna is free from any obstacles from all directions to avoid the possibility of antenna damage (refer to diagram at right).
4. When installing an external antenna you must connect the SMA jack located inside the receiver and make sure to set the jumper to "EXT" position (refer to diagram below).



5. For better reception, make sure the receiver is in an upright position.
6. Drill two holes (10mm in diameter) on the control panel or location where the receiver is to be installed (refer to Fig. 19 on page 35).
7. Make sure the two bolts are tightened after installation.
8. For system wiring please refer to page 33.

## 6.4 SYSTEM TESTING

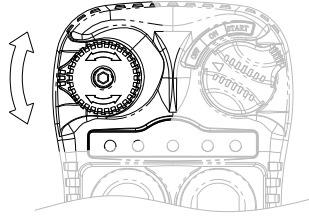
1. Turn on the power source to the receiver and test the MAIN relay output by pressing the red emergency stop button and observe that it properly opens and closes the mainline disconnect contactor.
2. Test the operation of each function to ensure it corresponds to the transmitter direction labels or the pendant it is replacing.
3. Test the limit switches (if any) to see if they are working properly.
4. If your new remote control is replacing an existing pendant, make sure it is completely disconnected and placed in a safe location to prevent unwanted control commands.

# 7. OPERATING PROCEDURE

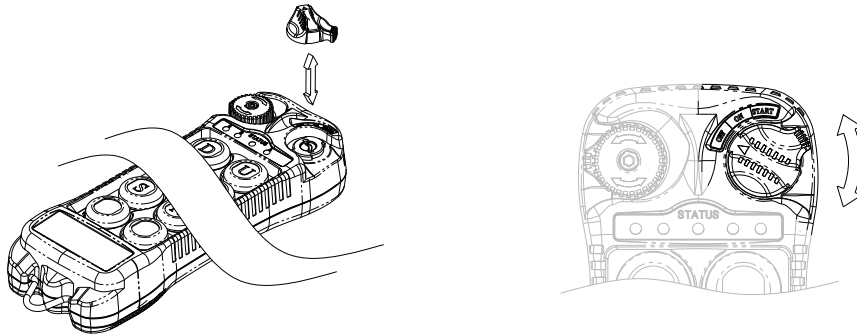
## 7.1 TRANSMITTER OPERATION

### 7.1.1. General Operating Procedure

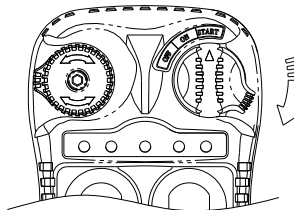
- a. Reset the red emergency stop button located on the top left hand side of the transmitter handset by rotating it either clockwise or counter clockwise. The red button will pop up.



- b. Turn on the transmitter power by inserting the black-colored key into the power key slot (located on the top right hand side of the transmitter handset) and rotate it clockwise to the "On" position.



- c. After turning on the transmitter power, check the Status LED on the transmitter handset for any sign of system irregularities (refer to "Status Light Indicators & Warnings" on page 41). If the system is normal, the Status LED will light up green for two (2) seconds.
- d. If there are no signs of any system irregularities, then rotate the power key further clockwise to "Start" position for up to 2 seconds - this will activate the receiver MAIN (depends on JP3 setting on page 30). Thereafter, the same "Start" position will become an auxiliary function with momentary contact (refer to page 26).



- e. Now press any push button on the transmitter handset to operate the crane or equipment. During transmitter inactivity (push buttons not pressed), the transmitter will automatically switch to standby mode, with an orange blink on the Status LED at every 4-second interval.
- f. In case of an emergency, pressing the red emergency stop button will immediately disconnect the receiver mainline (Status LED blinks red). To reset the emergency stop button, just rotate the red button either clockwise or counter-clockwise so it pops up. When the green light appears, rotate the power key to "Start" position to resume operation (depends on JP3 setting on page 29).
- g. After 5 minutes of inactivity (push buttons have not been pressed) the receiver MAIN will be disconnected temporarily (depends on JP1 & JP2 settings on page 29). To resume operation just rotate the power key switch to the START position to reconnect the receiver MAIN.
- h. Turn off the transmitter power by rotating the power key counter-clockwise to the "Off" position; it will disconnect the transmitter power and the receiver MAIN altogether. Turn it further counter-clockwise to release the key.

### ***7.1.2. Tandem Select Operating Procedure***

The Flex EX Tandem system is capable of operating one or two cranes independently or simultaneously (A / B / A+B).

#### **SELECTING CRANE A, B OR A+B:**

**To select Crane A:** Rotate the selector switch to position "A". Release the E-Stop and rotate the key switch to "Start". This will pull in the MLC (mainline contactor) for Crane A operation.

**To select Crane B:** Depress the E-Stop while the selector is still on "A". Rotate the selector switch to position "B". Release the E-Stop and rotate the key switch to "Start".

**To select Both A and B:** Rotate the selector switch to position "A+B". Rotate the key switch to "Start".

**To release either A or B:** Rotate the selector switch to position "A" or "B". Depress the E-Stop. To resume operation on the crane, make sure the crane is still powered, rotate to that crane's position and release the E-Stop.

*NOTE: The E-Stop MUST be pressed to release the 1st crane before selecting the 2nd crane.*

For example:

An operator is controlling crane A, and crane B is blocking the way. He selects "B" on the remote by turning the selector, moves crane B out of the way, then reselects "A" and continues on with original load. This condition prevents crane B from being operated by any other controller until the inactivity timer on crane B's receiver runs down. To avoid this condition, the operator should select crane B in the following manner:

**When switching from crane B back to crane A, the operator MUST press the E-Stop (to break mainline contact on crane B), turn back to crane A, release the E-Stop and restart crane A.**

The operator doesn't need to turn transmitter off then on again.

**FOR TANDEM SYSTEMS WITH DEDICATED TRANSMITTERS:**

The following chart should be referred to when setting up two separate systems for tandem operation:

UNIT	CHANNEL *	TYPE	RX Channel Type
TX A	x	1	n/a
TX B	x+2	2	n/a
Tandem TX AB	x+1	1	n/a
RX A	x	1	4**
RX B	x	2	4**

\* For Transmitter channel settings, TX B will be set two channels higher than TX A, regardless of selected channel.

\*\* RX channel type is set on receiver dipswitch positions 7 and 8 (see RX Auto-Scan setting below).

**Type 3:** SCAN TWO CHANNELS ONLY (can be used for Tandem operations with a dedicated receiver but is **not recommended**) switch 7 UP, switch 8 DOWN

**\*\*Type 4:** SCAN THREE CHANNELS ONLY (used for Tandem operations) switch 7 and 8 UP (**Default Setting**)

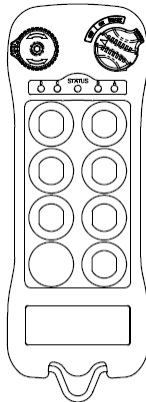
SYSTEM A

TX: Ch. 1  
Type: 1

RX: Ch. 1  
Type: 1

RX Channel  
Type: 4

(RX dipswitch 7 UP,  
8 UP)



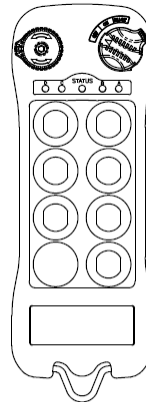
SYSTEM B

TX: Ch. 3  
Type: 2

RX: Ch. 1  
Type: 2

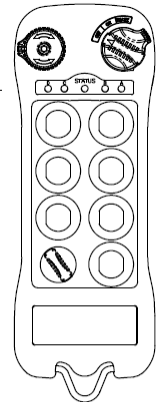
RX Channel  
Type: 4

(RX dipswitch 7 UP,  
8 UP)



TANDEM TX

TX: Ch. 2  
Type: 1



NOTE: "PITCH/CATCH" FEATURE SHOULD BE DISABLED FOR THIS APPLICATION. TO DISABLE, SET RECEIVER DIPSWITCH 4 (FOR FLEX 8EX) OR 6 (FOR FLEX 12EX) TO THE FOLLOWING: DIP 7 UP, ALL OTHERS DOWN (00000010)

**FOR TANDEM SYSTEMS *WITHOUT* DEDICATED TRANSMITTERS:**

The following chart should be referred to when setting up two separate systems for tandem operation:

UNIT	CHANNEL*	TYPE	RX Channel Type
TX A	x	1	n/a
TX B	x+1	2	n/a
RX A	x	1	3**
RX B	x	2	3**

\* For Transmitter channel settings, TX B will be set one channel higher than TX A, regardless of selected channel.

\*\* RX channel type is set on receiver dipswitch positions 7 and 8 (see RX Auto-Scan setting below).

**Type 3:** SCAN TWO CHANNELS ONLY (*used for Tandem operations*) switch 7 UP, switch 8 DOWN

**Type 4:** SCAN THREE CHANNELS ONLY (*used for Tandem operations*) switch 7 and 8 UP


*NOTE: Either setting may be used in tandem systems without dedicated transmitters (transmitters without the rotary switch) but it is critical that both receivers are set to the same channel scanning setting.*

**SYSTEM A**

TX: Ch. 1  
Type: 1

RX: Ch. 1  
Type: 1

RX Channel  
Type: 3  
(RX dipswitch 7 UP,  
8 DOWN)

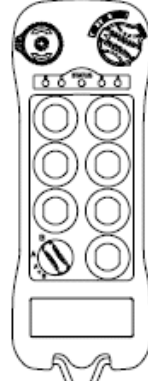


**SYSTEM B**

TX: Ch. 2  
Type: 2

RX: Ch. 1  
Type: 2

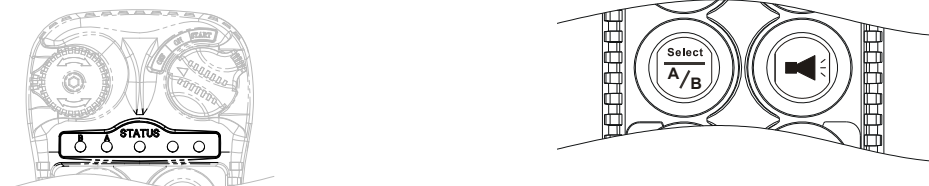
RX Channel  
Type: 3  
(RX dipswitch 7 UP,  
8 DOWN)



**NOTE: "PITCH/CATCH" FEATURE SHOULD BE DISABLED FOR THIS APPLICATION. TO DISABLE, SET RECEIVER DIPSWITCH 4 (FOR FLEX 8EX) OR 6 (FOR FLEX 12EX) TO THE FOLLOWING: DIP\_7 UP, ALL OTHERS DOWN (00000010)**

**7.1.3. Push Button Select A/B Operating Procedure**

Pressing the "Select A/B" push button will toggle between output relay A, B and A+B respectively. There are 4 different types of Select A/B sequences available; please refer to page 17 for instructions on how to set Select A/B functions.

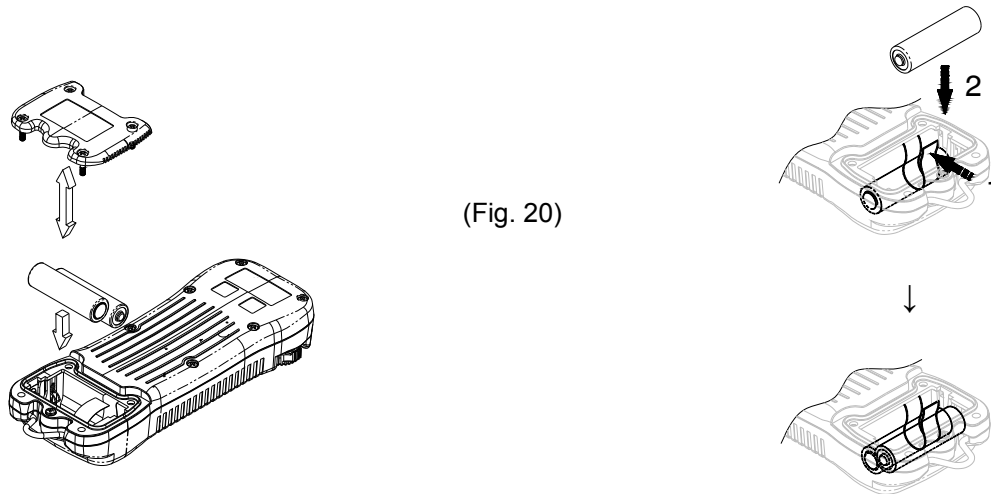


### 7.1.4. 3<sup>rd</sup> Speed Push Button Operating Procedure

When a push button is held at 2<sup>nd</sup> speed, pressing the 3<sup>rd</sup> Speed push button one time will activate the 3<sup>rd</sup> speed output relay (toggled). If the operator wants 2<sup>nd</sup> speed again, just press the 3<sup>rd</sup> Speed push button one more time.

### 7.1.5. Changing Transmitter Batteries

Change the transmitter batteries by unscrewing the battery cover located on the backside of the transmitter (refer to Fig. 20 below). During battery installations make sure that the blue ribbon is centered between the two batteries. After changing the batteries make sure that all screws are tightened to avoid water, moisture, dirt, grease, or other liquid penetration.



(Fig. 20)

## 7.2 STATUS LIGHT INDICATORS & WARNINGS

### 7.2.1. Transmitter STATUS Light Indication

Type	Display Type	Indication
1	Constant red	Voltage goes below 1.9V at initial power on - transmitter power shuts off.
		Voltage goes below 1.8V during operation - transmitter power shuts off. Turn the power off to disengage the receiver main.
2	1 red blink followed by a 2-second pause	Voltage goes below 1.85V during operation - change batteries immediately.
3	2 red blinks followed by a 2-second pause	The push button is defective after turning on the transmitter power.
4	No light displayed	When a defective push button condition occurs (2 red blinks, type 3 above), find out which push button is defective by pressing all the push buttons on the transmitter one at a time. If the push button is in good working order, the LED will not light up when pressed. If the push button is defective the LED will continue to display 2 red blinks when pressed.
5	3 red blinks followed by a 2-second pause	EEPROM error.
6	4 red blinks followed by a 2-second pause	Transmitting error; system cannot lock on to the designated channel.
7	Constant green for up to 2 seconds	Transmitter power on with no faults detected (prior to initiating the START function).
8	Blinking green	Push button pressed, signal transmitted.
9	Slow red blinks	Stop command initiated with receiver MAIN deactivated.
10	1 orange blink every 4 seconds	Transmitter on standby.

### 7.2.2. Receiver STATUS Light Indication

Type	Display Type	Indication
1	Fast green blinks	Decoding in process
2	Slow green blinks	Decoding on standby
3	Slow red blinks	Stop command initiated with receiver MAIN deactivated
4	Two red blinks	Receiver MAIN is jammed or defective
5	Fast red blinks	Incorrect transmitter serial number/ID code
6	Constant red	Receiver under-voltage, LV output relay activated
7	No light displayed	Decoding microprocessor is defective

### 7.2.3. Receiver SQ Light Indication

Type	Display Type (Red)	Indication
1	On	Transmission received
2	Off	No transmission
3	Blinks intermittently	Other radio interference

### 7.2.4. Receiver POWER Light Indication

Type	Display Type (Red)	Indication
1	On	Power to receiver
2	Off	No power to receiver

### 7.2.5. Receiver COM Light Indication

Type	Display Type (Red)	Indication
1	On	Power to relay board
2	Off	No power to relay board

## 7.3 TROUBLESHOOTING TIPS

Problems	Possible Reasons	Suggestions
<b>No response when transmitter push button is pressed (Improper startup &amp; settings)</b>	Transmitter low battery power	Check the transmitter battery level.
	Emergency stop button activated prior to startup	Prior to turning on the transmitter power switch make sure that the red emergency stop button is elevated.
	Improper startup procedure	Redo the startup procedure by holding the power key at "START" position for up to 2.0 seconds and then release.
	Incorrect system RF channel	Check and make sure that the transmitter handset and receiver unit both have the same channel.
	Incorrect system serial number/ID code	Check and make sure that the transmitter handset and receiver unit both have the same serial number/ID code.
	System out of range	Make sure that the startup procedure is initiated within 100 meters (300 feet) from the receiver location.
<b>No response when transmitter push button is pressed (Damaged hardware)</b>	Defective transmitting and receiving module	Check the SQ display on the face of the receiver unit. If it does not light up when the push button is pressed then either the transmitting or receiving module is defective. First replace the transmitting module. If SQ display is still not lit when the push button is pressed then go ahead and replace the receiving module.
	Defective encoder board or decoder module	If still no response, then replace the transmitter encoder board. If still doesn't work then the decoder module is defective.
<b>No AC power to the receiver</b>	Incorrect input voltage	Make sure the source voltage is set correctly.
	Blown fuse	Check for any blown fuse.
	Incorrect wiring	Check input voltage connection.
<b>Outputs do not correspond to transmitter</b>	Incorrect output connection	Check the system wiring again. Please refer to the output contact diagram inside this manual or on the receiver cover.

# 8. SYSTEM SPECIFICATIONS

Frequency Range	:	433 - 434 MHz																		
Frequency Deviation	:	12.5 KHz																		
Number of Channels	:	62 channels																		
Modulation	:	Digital Frequency Modulation based on Manchester Code, 20bit address, 32bit CRC Parity Check and Hamming Code.																		
Encoder & Decoder	:	Microprocessor-controlled																		
Transmitting Range	:	>100 Meters / 300 Feet																		
Frequency Control	:	Synthesized PLL (Phase Lock Loop)																		
Receiver Type	:	Frequency Auto Scanning																		
Receiver Sensitivity	:	-116dBm																		
Antenna Impedance	:	50 ohms																		
Responding Time	:	60 Milliseconds (average)																		
Transmitting Power	:	0.3mW																		
Enclosure Type	:	NEMA-4X																		
Enclosure Rating	:	IP-66																		
Output Contact Rating	:	250V @ 10 Amps																		
Transmitter Operating Voltage	:	DC 3.0V																		
Receiver Power Consumption	:	11.0 VA																		
Receiver Supply Voltage	:	<table> <thead> <tr> <th><u>Voltage Setting</u></th> <th><u>Min ~ Max</u></th> </tr> </thead> <tbody> <tr> <td>24VAC</td> <td>(22 ~ 26VAC)</td> </tr> <tr> <td>42VAC</td> <td>(38 ~ 46VAC)</td> </tr> <tr> <td>48VAC</td> <td>(43 ~ 53VAC)</td> </tr> <tr> <td>110VAC</td> <td>(104 ~ 126VAC)</td> </tr> <tr> <td>220VAC</td> <td>(207 ~ 253VAC)</td> </tr> <tr> <td>380VAC</td> <td>(351 ~ 429VAC)</td> </tr> <tr> <td>410VAC</td> <td>(400 ~ 480VAC)</td> </tr> <tr> <td>12/24VDC</td> <td>(9 ~ 36VDC)</td> </tr> </tbody> </table>	<u>Voltage Setting</u>	<u>Min ~ Max</u>	24VAC	(22 ~ 26VAC)	42VAC	(38 ~ 46VAC)	48VAC	(43 ~ 53VAC)	110VAC	(104 ~ 126VAC)	220VAC	(207 ~ 253VAC)	380VAC	(351 ~ 429VAC)	410VAC	(400 ~ 480VAC)	12/24VDC	(9 ~ 36VDC)
<u>Voltage Setting</u>	<u>Min ~ Max</u>																			
24VAC	(22 ~ 26VAC)																			
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220VAC	(207 ~ 253VAC)																			
380VAC	(351 ~ 429VAC)																			
410VAC	(400 ~ 480VAC)																			
12/24VDC	(9 ~ 36VDC)																			
Operating Temperature	:	-25°C -- 75°C / -13°F -- 167°F																		
Transmitter Dimension	:	184mm (L) x 69mm (W) x 34mm (H)																		
Receiver Dimension	:	363mm (L) x 228mm (W) x 70mm (H)																		
Transmitter Weight	:	242g / 8.5oz																		
Receiver Weight	:	2.5kg / 5.5lb																		